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## Corrected Trapezoidal Rule For The Riemann-Stieltjes Integral

**Abstract.** This study investigates the derivation of a corrected trapezoidal rule for approximating the Riemann-Stieltjes integral. The corrected trapezoidal rule is derived by approximating certain monomial functions to obtain optimal method coefficients. The proposed method has an accuracy of order three. Furthermore, an error analysis is conducted to assess the accuracy of the obtained approximation. In the final section, numerical computations are presented to compare the performance of the proposed method with existing methods. The results demonstrate that the proposed method produces smaller errors compared to previously developed approaches.

**Keywords:** corrected trapezoidal rule, Riemann-Stieltjes integral; error term.

### I. INTRODUCTION

The Riemann-Stieltjes integral was originally introduced by Thomas Stieltjes in 1894 in his seminal work "Recherches sur les fractions continues", which was published in the Annales de la Faculté des Sciences de Toulouse [1]. The Riemann-Stieltjes integral generalizes the standard Riemann integral by introducing a second integrator function, thereby achieving greater flexibility in mathematical modeling and analysis. Its most significant application is in probability theory and stochastic analysis, where it is an essential tool for describing probability distributions. Owing to its broad applicability, the Riemann-Stieltjes integral has also been widely applied in numerical analysis and differential equation studies, and thus remains very much an active area of research and development.

Various quadrature rules have been developed to approximate the Riemann-Stieltjes integral with the aim of achieving higher accuracy. Mercer [2] proposed a trapezoidal rule for the Riemann-Stieltjes integral, leading to Hadamard's inequality for general integrals. Later, Mercer [3] extended this work by developing the Midpoint and Simpson's 1/3 rules using the concept of relative convexity. The trapezoidal rule has also been modified for Riemann-Stieltjes integrals by Zhao and Zhang [6, 7], by including the value of the derivative at the endpoint and the derivative at the midpoint. Zhao and Zhang [8] also modified Simpson's 1/3 rule to approximate this integral. Furthermore, Zhao, Zhang, and Ye [5] introduced a composite Trapezoidal rule for the Riemann-Stieltjes integral. Additionally, Memon et al. [9] proposed efficient derivative-based and derivative-free quadrature schemes, verified through numerical experiments. In another study, Memon et al. [10, 11, 12] modified Simpson's 1/3 rule by incorporating Heronian, centroidal, and harmonic mean derivative values to approximate the Riemann-Stieltjes integral. Memon [13] also modified the four-point quadrature to approximate the Riemann-Stieltjes integral. Several adjustments have been made in the numerical method over time to get better performance based on our needs. For example, a recent variation of the Double Midpoint Rule for approximating the Riemann-Stieltjes Integral [14].

Building on the approach presented in [4], this study aims to modify the corrected Trapezoidal rule to improve the numerical approximation of the Riemann-Stieltjes integral. The article provides a comprehensive analysis of the corrected Trapezoidal rule in the context of the Riemann-Stieltjes integral, including the derivation of its error formulation. Furthermore, nu-

2 merical simulations are conducted to evaluate the accuracy and effectiveness of the proposed  
 3 method.

## 4 II. RESULTS AND DISCUSSION

5 This se<sup>2</sup>on presents the findings of the study, including the development of the Corrected  
 6 Trapezoidal Rule for the Riemann-Stieltjes integral, its associated error analysis, and numerical  
 7 examples demonstrating its effectiveness. The proposed method is analyzed in detail to evaluate  
 8 its accuracy and applicability in numerical integration.

### 1 2.1. Corrected Trapezoidal Rule For The Riemann-Stieltjes Integral

4 In this section, the formulation of the corrected Trapezoidal Rule (CTRS) for the Riemann-  
 10 Stieltjes integral is introduced. The formulation, presented in Theorem 2.1, is derived by ap-  
 11 proximating monomial functions at specific powers and solving a nonlinear equation that de-  
 12 termines the coefficients of this approximation.

6 **Theorem 1** Let  $f'(s)$  and  $g(s)$  are continuous on  $[v, w]$  and  $g(t)$  is increasing function in the  
 14 interval  $[v, w]$ . The corrected Trapezoidal Rule (CTR) for the Riemann-Stieltjes integral is

$$15 \begin{aligned} CTRS = & \left( -g(v) + \frac{6}{(v-w)^2} \int_v^w \int_v^s g(x) dx ds + \frac{12}{(v-w)^3} \int_v^w \int_v^s \int_v^y g(x) dx dy ds \right) f(v) \\ & + \left( g(w) - \frac{6}{(v-w)^2} \int_v^w \int_v^s g(x) dx ds - \frac{12}{(v-w)^3} \int_v^w \int_v^s \int_v^y g(x) dx dy ds \right) f(w) \\ & - \left( \int_v^w g(s) ds + \frac{4}{(v-w)} \int_v^w \int_v^s g(x) dx ds + \frac{6}{(v-w)^2} \int_v^w \int_v^s \int_v^y g(x) dx dy ds \right) f'(w) \\ & + \left( \frac{-2}{(v-w)} \int_v^w \int_v^s g(x) dx ds - \frac{6}{(v-w)^2} \int_v^w \int_v^s \int_v^y g(x) dx dy ds \right) f'(v). \end{aligned} \quad (1)$$

16 *Proof.* The general form of corrected trapezoid rule is [15, h. 174]

$$17 \quad CT = \frac{w-v}{2} (f(v) + f(w)) - \frac{(w-v)^2}{12} (f'(w) - f'(v)), \quad (2)$$

18 Obtaining the corrected trapezoidal rule for the Riemann-Stieltjes integral requires rewriting  
 Equation (2) as follows:

$$19 \quad CT = a_0 f(v) + b_0 f(w) - [c_0 f'(w) - d_0 f'(v)] \quad (3)$$

The values of  $a_0, b_0, c_0$ , and  $d_0$  will be determined such that the integral in Equation (3) is exact

20 for  $f(s) = 1, s, s^2, s^3$  and obtain the following equations

$$\int_v^w 1 dg(s) = a_0 + b_0; \quad (4)$$

$$\int_v^w s dg(s) = a_0 v + b_0 w - c_0 + d_0; \quad (5)$$

$$\int_v^w s^2 dg(s) = a_0 v^2 + b_0 w^2 - 2 w c_0 + 2 v d_0; \quad (6)$$

$$\int_v^w s^3 dg(s) = a_0 v^3 + b_0 w^3 - 3 c_0 w^2 + 3 d_0 v^2. \quad (7)$$

21 The Riemann-Stieltjes integral formula is applied to the left side of equations (4), (5), (6), and  
22 (7) to derive the following expression

$$a_0 + b_0 = g(w) - g(v); \quad (8)$$

$$a_0 v + b_0 w - c_0 + d_0 = w g(w) - v g(v) - \int_v^w g(s) ds; \quad (9)$$

$$a_0 v^2 + b_0 w^2 - 2 w c_0 + 2 v d_0 = w^2 g(w) - v^2 g(v) - 2 \int_v^w g(s) dt \\ + 2 \int_v^w \int_v^t g(x) dx ds; \quad (10)$$

$$a_0 v^3 + b_0 w^3 - 3 c_0 w^2 + 3 d_0 v^2 = b^3 g(b) - a^3 g(a) - 3 b^2 \int_v^w g(s) ds \\ + 6 b \int_v^w \int_v^s g(x) dx ds \\ - 6 \int_v^w \int_v^s \int_v^y g(x) dx dy ds. \quad (11)$$

1 The coefficients  $a_0, a_1, c_0$ , and  $c$  are determined by solving the system of equations (8), (9),  
2 (10), and (11), yielding the following results:

$$a_0 = -g(v) + \frac{6}{(v-w)^2} \int_v^w \int_v^s g(x) dx ds + \frac{12}{(v-w)^3} \int_v^w \int_v^t \int_v^y g(x) dx dy ds \\ b_0 = g(w) - \frac{6}{(v-w)^2} \int_v^w \int_v^t g(x) dx ds - \frac{12}{(v-w)^3} \int_v^w \int_v^t \int_v^y g(x) dx dy ds \\ c_0 = \int_v^w g(s) ds + \frac{4}{(v-w)} \int_v^w \int_v^t \text{g}(x) dx ds + \frac{6}{(v-w)^2} \int_v^w \int_v^t \int_v^y \text{g}(x) dx dy ds \\ d_0 = \frac{-2}{(v-w)} \int_v^w \int_v^t g(x) dx ds - \frac{6}{(v-w)^2} \int_v^w \int_v^t \int_v^y g(x) dx dy ds$$

3

□

4 Based on Theorem (1), it can be seen that for  $f(s) = s^4$  the quadrature is not equal.  
5 Therefore, the accuracy of this method is 3.

## 2.2. Error Term Of Corrected Trapezoidal Rule For The Riemann-Stieltjes Integral.

In this section, the error form of the corrected Trapezoidal Rule for the Riemann-Stieltjes integral is given. We use the precision notion to calculate the error form associated to the difference between the quadrature formula for the monomial  $\frac{s^{r+1}}{(r+1)!}$  and the exact value of the

$$\frac{1}{(r+1)!} \int_v^w s^{r+1} dx = \frac{w^{r+2} - v^{r+2}}{(r+2)!},$$

where  $r$  is the precision of the quadrature formula.

**Theorem 2** Suppose that  $f'(s)$  and  $g'(s)$  are continuous on  $[v, w]$  and  $g(s)$  is increasing there. The corrected Trapezoidal Rule (CTRS) for the Riemann-Stieltjes integral with the error term is

$$\begin{aligned} R(f) = & \left[ \left( \frac{v^2 w - 2v w^2 + w^3}{12} \right) \int_v^w \int_v^s g(x) dx ds \right. \\ & + \left( \frac{v - w}{2} \right) \int_v^w \int_v^s \int_v^y g(x) dx dy ds \\ & \left. + \int_v^w \int_v^s \int_v^z \int_v^y g(x) dx dy dz ds \right] f^{(4)}(\xi) g'(\eta) \end{aligned} \quad (12)$$

*Proof.* The error in the equation (12) is obtained by using a monomial of order 4, which

$$f(s) = \frac{s^4}{4!} \quad (13)$$

The exact solution of equation (13) is

$$\begin{aligned} \frac{1}{4!} \int_v^w t^4 dg = & \frac{1}{24} (w^4 g(w) - v^4 g(v)) - \frac{w^3}{6} \int_v^w g(s) ds + \frac{w^2}{6} \int_v^w \int_v^s g(x) dx ds \\ & - w \int_v^w \int_v^s \int_v^y g(x) dx dy ds + \int_v^w \int_v^s \int_v^z \int_v^y g(x) dx dy dz ds \end{aligned} \quad (14)$$

Based on Theorem (1), the approximate solution is

$$\begin{aligned} CNTR = & \frac{1}{24} (w^4 g(w) - v^4 g(v)) - \frac{w^3}{6} \int_v^w g(s) ds \\ & - \frac{-v^2 + 2v w + 5w^2}{12} \int_v^w \int_v^s g(x) dx ds \\ & - \frac{v - w}{2} \int_v^w \int_v^s \int_v^y g(x) dx dy ds \end{aligned} \quad (15)$$

The error term is obtained by subtracting the exact solution (14) from the approximate solution

11 (15), hence

$$\begin{aligned}
 R(f) = & \left[ \left( \frac{v^2 w - 2 v w^2 + w^2}{12} \right) \int_v^w \int_v^s g(x) dx ds \right. \\
 & + \left( \frac{v - w}{2} \right) \int_v^w \int_v^s \int_v^y g(x) dx dy ds \\
 & \left. + \int_v^w \int_v^s \int_v^y \int_v^z g(x) dx dy dz ds \right] f^{(4)}(\xi) g'(\eta)
 \end{aligned}$$

12

□

### 13 2.3. Numerical Examples

1 To validate the theoretical findings, numerical examples are given to illustrate the performance of the Corrected Trapezoidal Rule for Riemann-Stieltjes integrals (*CTRS*). These examples compare the proposed method with existing numerical integration techniques, namely 2 Trapezoidal Rule for Riemann-Stieltjes integral (*AT*), Simpson Centroidal Riemann-Stieltjes 3 integral (*SC*), Simpson Heronian Riemann-Stieltjes integral (*SH*), and Simpson Harmonic 4 Riemann-Stieltjes integral (*SHM*), highlighting its efficiency and precision.

5 **Example 1** Integral  $\int_{0.0}^{1.0} s^3 d(\sin s^2)$ ,  $\int_{0.0}^{1.0} e^{-s} d(\cos s)$ ,  $\int_0^1 \ln(s+1) d(\cos s)$  are approximated 6 by using *CTRS*, *AT*, *SC*, *SH*, and *SHM*.

Table 1. Comparison of computational results of *CTRS*, *AT*, *SC*, *SH*, and *SHM* methods

Methods	Integral		
	$\int_{0.0}^{1.0} s^3 d(\sin s^2)$	$\int_{0.0}^{1.0} e^{-s} d(\cos s)$	$\int_0^1 \ln(s+1) d(\cos s)$
	Error	Error	Error
<i>CTRS</i>	0.00000000000000	0.0003985494540	0.0008831519270
<i>AT</i>	0.00000000000000	0.0005691286670	0.0011528711856
<i>SC</i>	0.0119205077121	0.0010307315662	0.0011632818783
<i>SH</i>	0.0119205077121	0.0011843421351	0.0020109453758
<i>SHM</i>	0.0119205077121	0.0013987229536	0.0051128623031

9 The computational results in Table (??) compare five numerical integration methods:  
10 *CTRS*, *AT*, *SC*, *SH*, and *SHM*, with the *CTRS* method consistently demonstrating superior  
11 accuracy. In the first integral  $\int_0^1 s^3 d(\sin s^2)$ , all methods achieve zero error, indicating excellent  
12 performance for relatively simple integrals. However, the *CTRS* method stands out in more  
13 complex cases.

14 For the second integral  $\int_0^1 e^{-s} d(\cos s)$ , *CTRS* achieves the lowest error of 0.0003985494540,  
15 outperforming other methods such as *AT* and *SC*. This demonstrates its efficiency in handling  
16 exponential and trigonometric components with better numerical stability. Similarly, for the  
17 third integral  $\int_0^1 \ln(s+1) d(\cos s)$ , *CTRS* again records the smallest error of 0.0008831519270,  
18 indicating its robustness with logarithmic-trigonometric integrals.

19 Overall, the *CTRS* method consistently delivers minimal error across all tested integrals,  
20 especially in complex scenarios. Its superior precision makes it a reliable choice for mathematical  
21 and engineering applications requiring high numerical accuracy.

### 1 III. CONCLUSIONS AND FUTURE RESEARCH DIRECTION 2

2 In conclusion, the Corrected Trapezoidal Rule for the Riemann-Stieltjes integral is derived  
3 from the formulation of the Corrected Trapezoidal Rule itself. This method achieves third-  
4 order accuracy. The error expression for the Corrected Trapezoidal Rule in Riemann-Stieltjes  
5 integration is obtained by calculating the difference between the exact value and the quadrature  
6 formula applied to monomials of a certain degree. the Corrected Trapezoidal Rule for the  
7 Riemann-Stieltjes integral (*CTRS*) has proven to be a highly accurate and reliable numeri-  
8 cal method. Its minimal error across various types of integrals, including polynomial, expo-  
9 nential, trigonometric, and logarithmic functions, highlights its versatility and robustness. The  
10 computational results clearly demonstrate that *CTRS* outperforms other conventional methods  
11 such as *AT*, *SC*, *SH*, and *SHM*, particularly in complex integration scenarios. Future research  
12 could focus on modifying other numerical methods to approximate the Riemann-Stieltjes in-  
13 tegral. Exploring variations of classical methods might reveal new techniques that enhance  
14 accuracy or computational efficiency.

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